

## Impedance Matching

### 1 Introduction

Impedance matching is the process to match the load  $Z_L$  to a transmission line by a matching network, as depicted in Fig. 1. Recall that the reflections are eliminated under the matched condition. Impedance matching is important for the following reasons:

- To achieve maximum power transfer and minimize power loss.
- To improve signal-to-noise ratio.
- To reduce amplitude and phase errors for power distribution networks, e.g., antenna arrays.

There are many choices regarding matching network design, but the following factors must be considered in the selection of the network:

- Complexity
- Bandwidth
- Implementation
- Adjustability

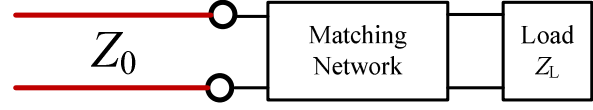


Fig. 1: Impedance matching

### 2 Matching with Lumped Elements (L Networks)

The L-section is considered the simplest type of matching network. There are two possible configurations, as depicted in Fig. 2. (a) is the network for  $\text{Re}[Z_L] > Z_0$ , while (b) is the network for  $\text{Re}[Z_L] < Z_0$ . Note that in both configurations, two components ( $jX$ ,  $jB$ ) are required in order to have degree of freedom 2, since the load impedance is generally complex.

Consider Fig. 2(a). Let  $Z_L = R_L + jX_L$ , then the impedance seen looking into the matching network followed by the load impedance must be equal to  $Z_0$ , i.e.,

$$Z_0 = jX + \frac{1}{jB + 1/(R_L + jX_L)}.$$

Rearranging and separating into real and imaginary parts yield

$$B(XR_L - X_L Z_0) = R_L - Z_0; X(1 - BX_L) = BZ_0 R_L - X_L$$

Solving the above equations yields

$$B = \frac{X_L \pm \sqrt{R_L / Z_0} \sqrt{R_L^2 + X_L^2 - Z_0 R_L}}{R_L^2 + X_L^2}.$$

Note that the argument inside the second square root is always positive since  $R_L > Z_0$ . The series reactance can be found as

$$X = \frac{1}{B} + \frac{X_L Z_0}{R_L} - \frac{Z_0}{BR_L}.$$

Note also that two solutions are generally possible. One must consider the above factors in deciding which L network to use.

Likewise, for the network in Fig. 2(b), the matched condition is given by

$$\frac{1}{Z_0} = jB + \frac{1}{R_L + j(X + X_L)}.$$

Rearranging and separating into real and imaginary parts yield

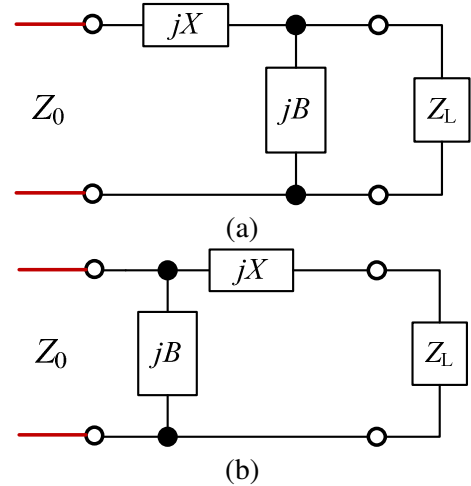


Fig. 2: L-section matching networks.

## Impedance Matching

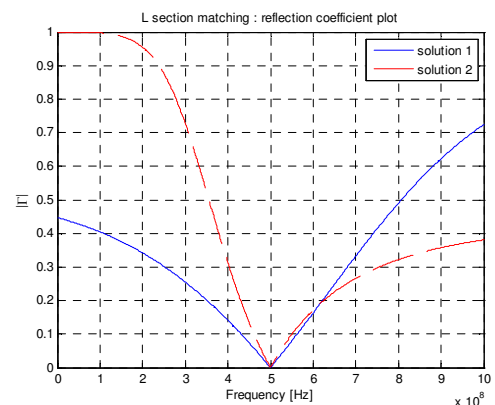
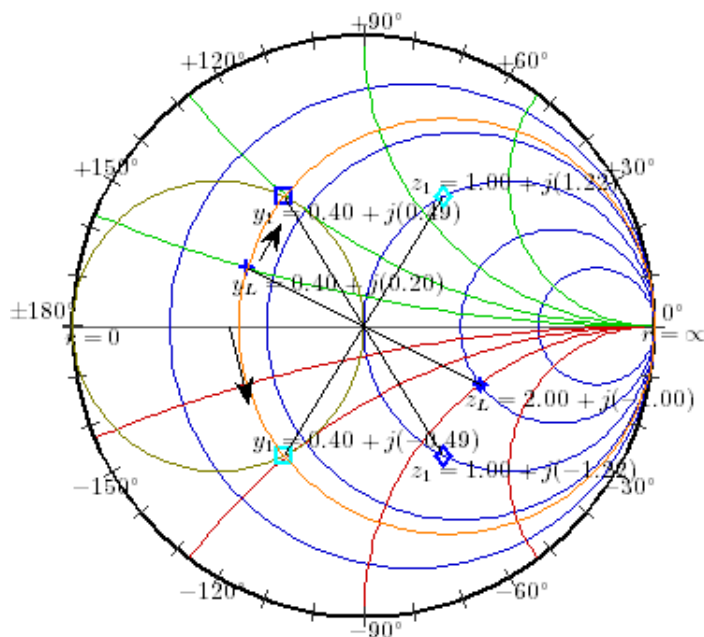
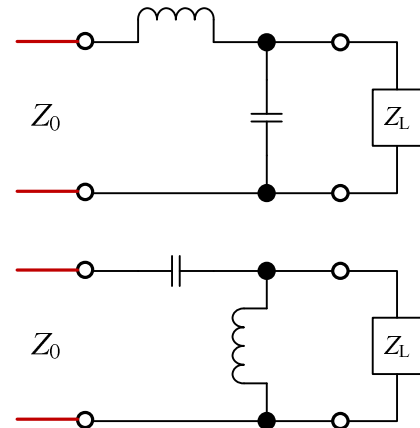
$$BZ_0(X + X_L) = Z_0 - R_L; \quad X + X_L = BZ_0R_L.$$

Solving for  $X$  and  $B$  gives

$$X = \pm \sqrt{R_L(Z_0 - R_L)} - X_L; \quad B = \frac{\pm \sqrt{(Z_0 - R_L)/R_L}}{Z_0}.$$

Note that  $R_L < Z_0$  in this case, so the argument of the square root is always positive.

**Example 1** Design an L-section matching network to match a series  $RC$  load with an impedance  $Z_L = 200 - j100 \, \Omega$ , to a  $100 \, \Omega$  line, at a frequency of  $500 \, \text{MHz}$ .



### 3 Single-Stub Tuning

The impedance matching using L-sections discussed previously requires lumped elements that might not be available, thus it is not practical in some cases. The single-stub tuning is the matching technique that uses a single open-circuited or short-circuited length of transmission-line (a “stub”), connected either in parallel or in series with the transmission feed line at a certain distance from the load. Note that there are two design parameters, namely the length of the stub and the distance from the load, which contribute degree of freedom 2, as in the matching with L-sections.

The choice of open-circuited stub or short-circuited stub depends on the type of transmission line media. For microstrip lines, open stubs are preferred due to ease of fabrication, while for coaxial lines

or waveguides, short stubs are more desirable since such open-circuited stubs tend to radiate, resulting in reactance changes.

## 3.1 Shunt Stubs

The single-stub shunt tuning circuit configuration is shown in Fig. 3. Refer to the figure, to match the impedance, it is required that

$$Y_0 = Y_{in} = Y_1 + Y_{stub}.$$

Since  $Y_{stub}$  is purely susceptance (i.e., zero conductance), the real part of  $Y_1$  must be equal to  $Z_0$ . Furthermore, the susceptance of  $Y_1$  must cancel out the susceptance of  $Y_{stub}$ , resulting in  $Y_{in}$  becomes  $Y_0$ . Using the Smith chart makes the design process easier. The first step is to find the distance such that the normalized admittance is on the  $1+jb$  circle. Then find the length such that the stub has susceptance  $-jb$ .

**Example 2** For a load impedance  $Z_L = 60 - j80 \Omega$ , design two single-stub (short circuit) shunt tuning networks to match this load to a  $50 \Omega$  line. Assuming that the load is matched at 2 GHz and the load consists of a resistor and a capacitor in series.

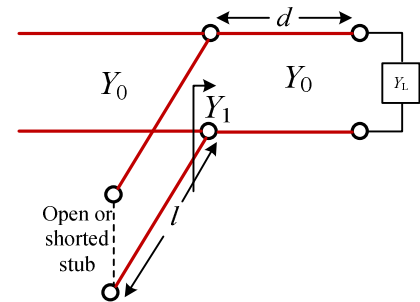
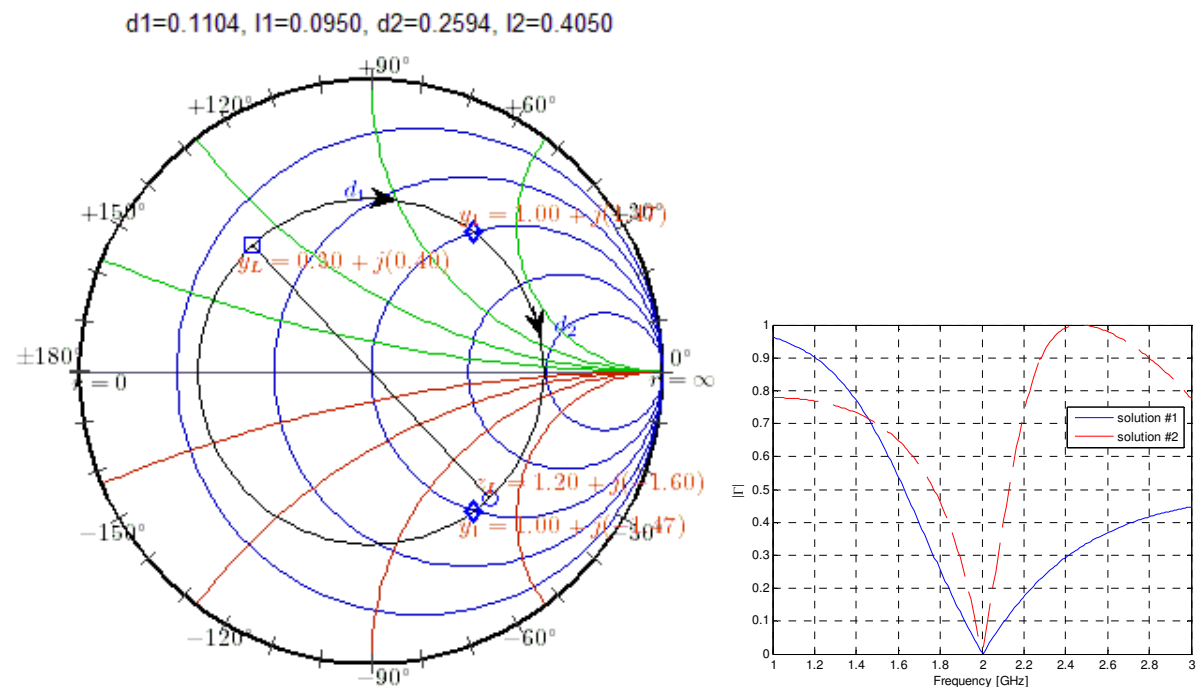


Fig. 3: Single-stub shunt tuning



## 3.2 Series Stubs

The single-stub series tuning circuit configuration is shown in Fig. 4. Refer to the figure, to match the impedance, it is required that

$$Z_0 = Z_{in} = Z_1 + Z_{stub}.$$

Since  $Z_{stub}$  is purely reactance (i.e., zero resistance), the real part of  $Z_1$  must be equal to  $Z_0$ . Furthermore, the reactance of  $Z_1$  must cancel out the reactance of  $Z_{stub}$ , resulting in  $Z_{in}$  becomes  $Z_0$ . As in the shunt tuning circuit design, using the Smith chart makes the design process easier. The first step is to find the distance such

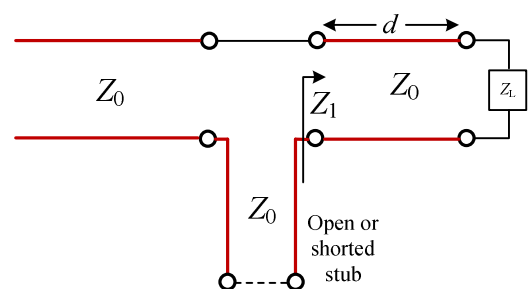
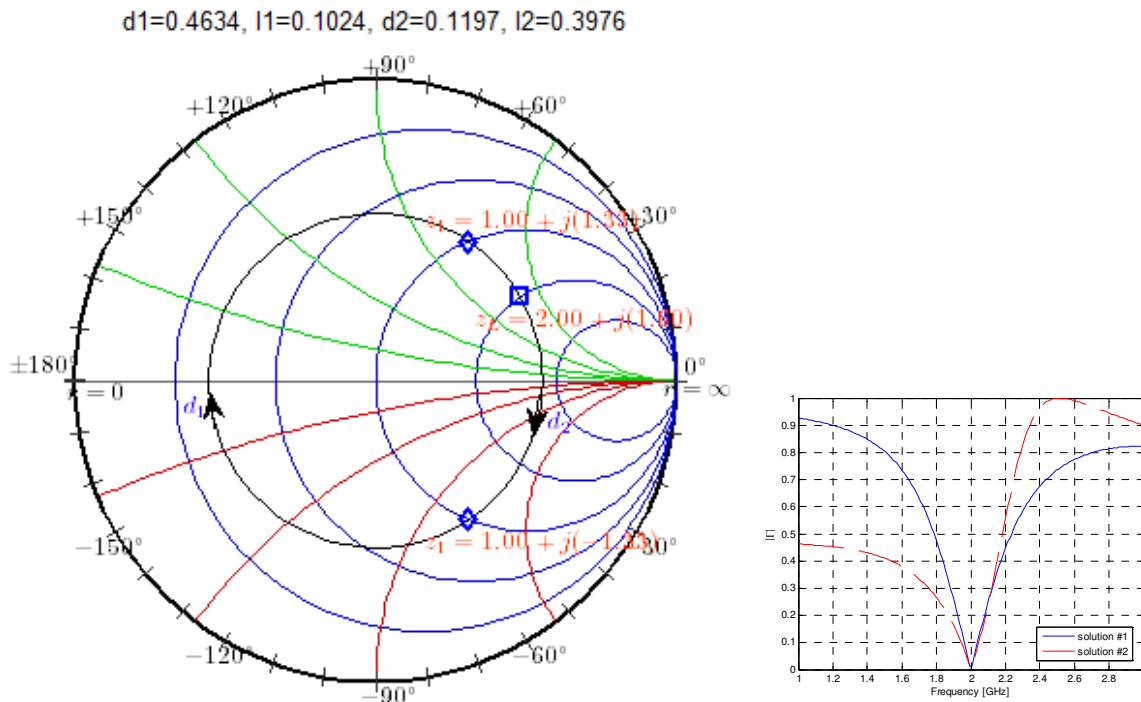


Fig. 4: Single-stub series tuning

that the normalized impedance is on the  $1+jx$  circle. Then find the length such that the stub has reactance  $-jx$ .

**Example 3** For a load impedance  $Z_L = 100 + j80 \Omega$ , design two single-stub (open circuit) series tuning networks to match this load to a  $50 \Omega$  line. Assuming that the load is matched at 2 GHz and the load consists of a resistor and an inductor in series.



## 4 Double-Stub Tuning

The single-stub tuner requires a variable length of line between the load and the stub, thus it is difficult to make it “adjustable”. The double-stub tuning shown in Fig. 5 uses 2 adjustable shunt stubs in fixed positions. However, the double-stub tuner cannot match **all** load impedances.

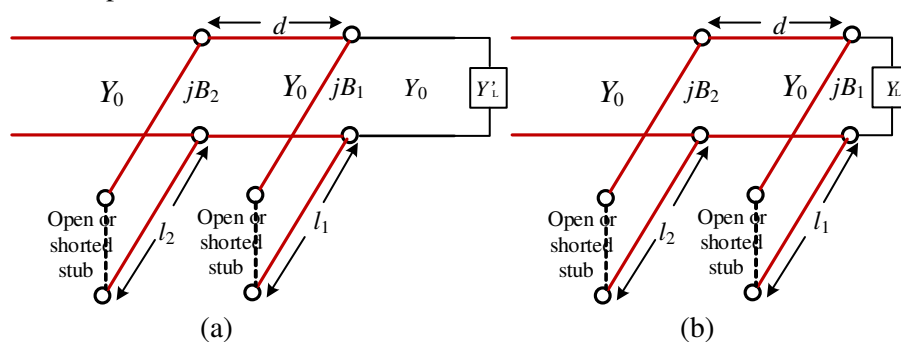


Fig. 5: Double-stub tuning (a) Original circuit with the load an arbitrary distance from the first stub (b) Equivalent circuit with the load transformed to the first stub.

The Smith chart solution can be illustrated in Fig. 6. First, locate  $y_L$  and draw the rotated  $1+jb$  circle with respect to the stub spacing  $d$ . Then move the load admittance onto the rotated  $1+jb$  circle (points  $y_1, y'_1$ ) using the susceptance  $b_1, b'_1$  of the stub. Next, move the points  $y_1, y'_1$  onto the  $1+jb$  circle (points  $y_2, y'_2$ ). Finally, add the susceptance  $b_2, b'_2$  to match the load impedance. Note that there are two possible solutions as in the case of single-stub tuning.

## Impedance Matching

Notice that if  $y_L$  is inside the shaded region in the figure, specified by  $g_0 + jb$  circle, it is impossible to move this admittance onto the rotated circle, which means that it cannot be matched by a double-stub tuner (i.e., there is no solution). Therefore, this shaded region forms a forbidden range of load admittances that cannot be matched by this double-stub tuner. Reducing the space  $d$  can lead to the reduction in the size of this forbidden region, however,  $d$  must be kept sufficiently large for fabricating two separate stubs. In addition, spacings near 0 or  $\lambda/2$  lead to matching networks that are very frequency sensitive. In practice, stub spacings are usually chosen as  $\lambda/8$  or  $3\lambda/8$ . Furthermore, if the length of line between the load and the first stub can be adjusted, then  $y_L$  can always be moved out of the forbidden region.

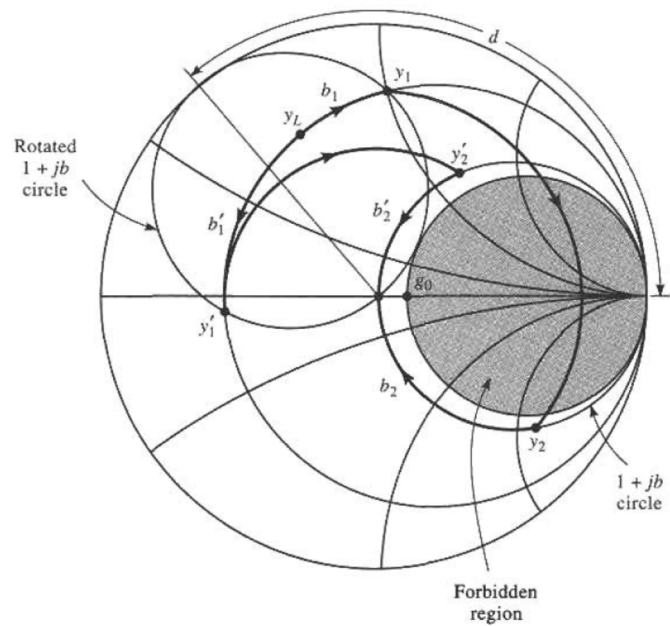
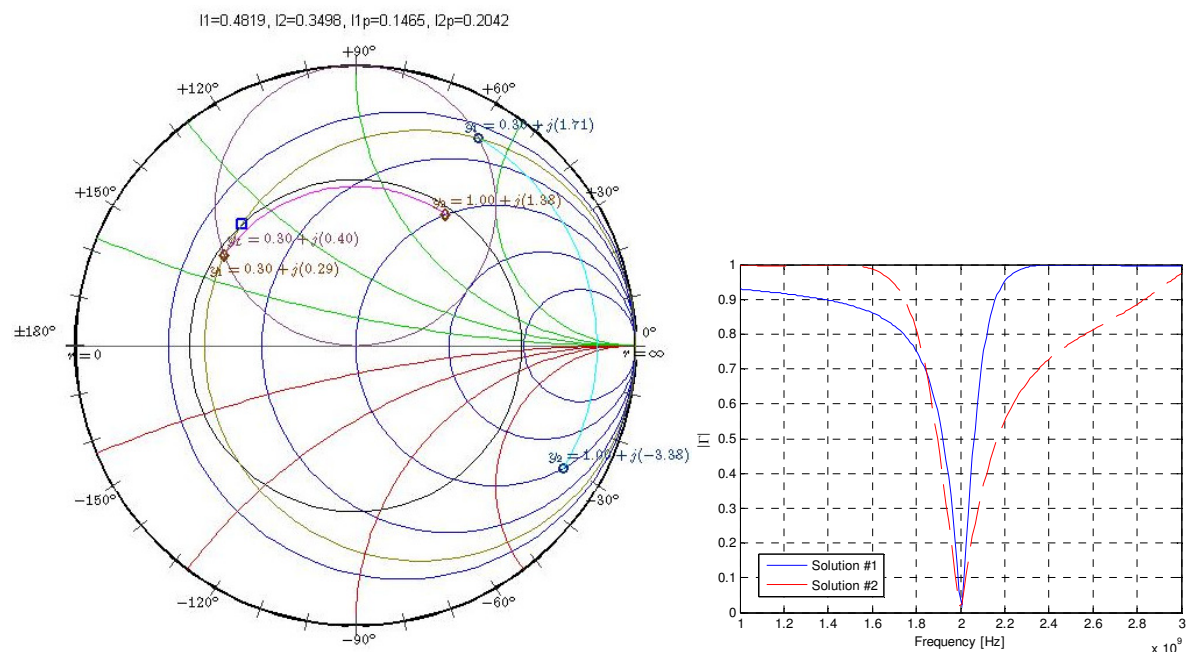


Fig. 6: Smith chart diagram for the operation of a double-stub tuner.

**Example 4** For a load impedance  $Z_L = 60 - j80 \, \Omega$ , design a shunt double-stub tuner to match this load to a  $50 \, \Omega$  line. The stubs are to be open-circuited and are spaced  $\lambda/8$  apart. Also, the load is assumed to consist of a  $60\Omega$ -resistor and a  $0.995\text{pF}$ -capacitor.



## 5 Quarter-Wave Transformer

Recall that, for a quarter-wavelength transmission line ( $\ell = \lambda/4$ ), the input impedance becomes

$$Z_{in} = Z_0^2 / Z_L \text{ or } Z_0^2 = Z_{in} Z_L.$$

## Impedance Matching

Therefore, a quarter-wavelength transmission line can be used to convert a resistive load to match a transmission line by choosing the proper characteristic impedance of the quarter-wavelength line. This is called a quarter-wave transformer. The general configuration of this quarter-wave transformer is shown in Fig. 6, where

$$Z_1^2 = Z_0 R_L.$$

To match an arbitrary  $Z_L$  using the quarter-wave transformer, one must somehow modify the load such that it becomes purely resistive.

This may be done by adding certain lumped elements, transmission line of certain length, tuning circuits or stubs.

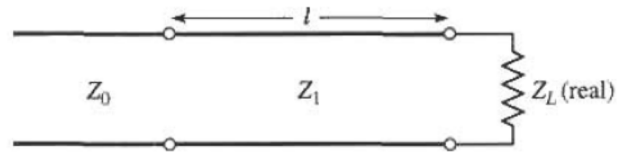


Fig. 6

Example 5 Repeat example 3 by using the quarter-wave transformer.

## 6 The Theory of Small Reflections

Quarter-wave transformers provide a simple mean of impedance matching, but cannot achieve broad bandwidth. To obtain more bandwidth, multisection transformers can be used.

### Single-section Transformer

Consider the single-section transformer shown in Fig. 7, the partial reflection and transmission coefficients are given by

$$\Gamma_1 = \frac{Z_2 - Z_1}{Z_2 + Z_1}; \Gamma_2 = -\Gamma_1; \Gamma_3 = \frac{Z_L - Z_2}{Z_L + Z_2};$$

$$T_{21} = 1 + \Gamma_1 = \frac{2Z_2}{Z_2 + Z_1}; T_{12} = 1 + \Gamma_2 = \frac{2Z_1}{Z_2 + Z_1}.$$

The total reflection can then be given in terms of an infinite sum of partial reflections and transmissions as follows:

$$\begin{aligned} \Gamma &= \Gamma_1 + T_{12}T_{21}\Gamma_3e^{-j2\theta} + T_{12}T_{21}\Gamma_3^2\Gamma_2e^{-j4\theta} + \dots \\ &= \Gamma_1 + T_{12}T_{21}\Gamma_3e^{-j2\theta} \sum_{n=0}^{\infty} \Gamma_2^n \Gamma_3^n e^{-j2n\theta} \end{aligned}$$

Using the geometric series

$$\sum_{n=0}^{\infty} x^n = \frac{1}{1-x}, \text{ for } |x| < 1,$$

$\Gamma$  can be rewritten as

$$\Gamma = \Gamma_1 + \frac{T_{12}T_{21}\Gamma_3e^{-j2\theta}}{1 - \Gamma_2\Gamma_3e^{-j2\theta}}.$$

Using  $\Gamma_2 = -\Gamma_1$ ,  $T_{21} = 1 + \Gamma_1$ ,  $T_{12} = 1 - \Gamma_1$  yields

$$\Gamma = \frac{\Gamma_1 + \Gamma_3e^{-j2\theta}}{1 + \Gamma_1\Gamma_3e^{-j2\theta}}.$$

If the discontinuities between the impedances  $Z_1, Z_2$  and  $Z_2, Z_L$  are small, then  $|\Gamma_1\Gamma_3| \ll 1$ , and

$$\Gamma \cong \Gamma_1 + \Gamma_3e^{-j2\theta}.$$

### Multisection Transformer

Now consider the multisection transformer shown in Fig. 8. This transformer consists of  $N$  equal-length (*commensurate*) sections of transmission lines. Partial reflection coefficients can be defined at each junction as

$$\Gamma_0 = \frac{Z_1 - Z_0}{Z_1 + Z_0}; \Gamma_n = \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n}; \Gamma_N = \frac{Z_L - Z_N}{Z_L + Z_N}.$$

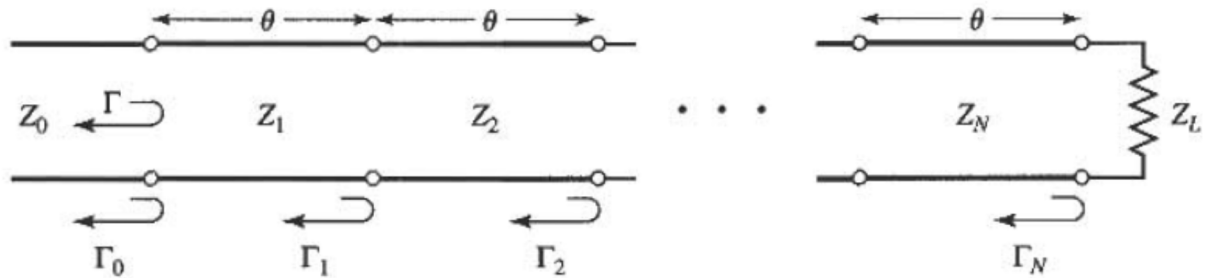


Fig. 8

We also assume that all  $Z_n$  increase or decrease monotonically across the transformer, and  $Z_L$  is real. This implies that  $\Gamma_n$  will be real and of the same sign. Then the total reflection coefficient  $\Gamma$  can be approximated as

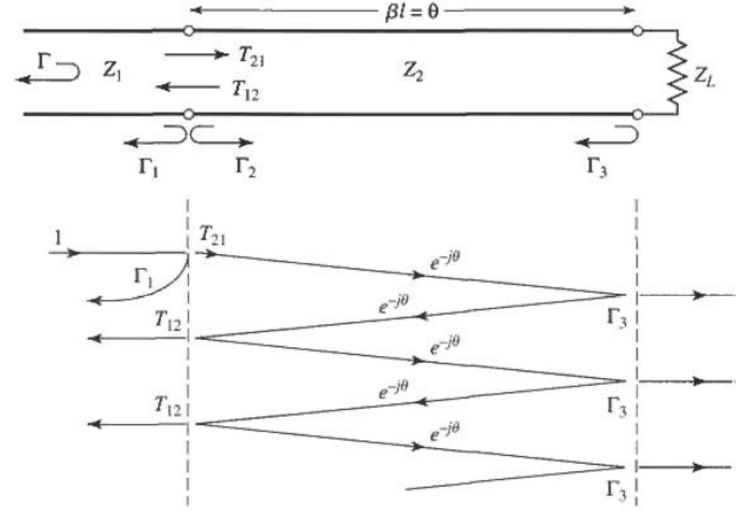


Fig. 7

$$\Gamma(\theta) = \Gamma_0 + \Gamma_1 e^{-j2\theta} + \Gamma_2 e^{-j4\theta} + \dots + \Gamma_N e^{-j2N\theta}.$$

Furthermore, assume that the transformer can be made symmetric, so that  $\Gamma_0 = \Gamma_N$ ,  $\Gamma_1 = \Gamma_{N-1}$ , etc. (Note that this does not imply that the  $Z_n$ 's are symmetrical.) Then,

$$\Gamma(\theta) = e^{-jN\theta} \left\{ \Gamma_0 (e^{-jN\theta} + e^{jN\theta}) + \Gamma_1 (e^{-j(N-2)\theta} + e^{j(N-2)\theta}) + \dots \right\}.$$

It follows that for  $N$  even,

$$\Gamma(\theta) = 2e^{-jN\theta} \left\{ \Gamma_0 \cos N\theta + \Gamma_1 \cos(N-2)\theta + \dots + \Gamma_n \cos(N-2n)\theta + \dots + \frac{1}{2} \Gamma_{N/2} \right\},$$

and for  $N$  odd,

$$\Gamma(\theta) = 2e^{-jN\theta} \left\{ \Gamma_0 \cos N\theta + \Gamma_1 \cos(N-2)\theta + \dots + \Gamma_n \cos(N-2n)\theta + \dots + \Gamma_{(N-1)/2} \cos \theta \right\}.$$

From these results, one can notice that any desired reflection response (as a function of  $\theta$ ) can be realized by choosing the proper  $\Gamma_n$ 's and using enough sections. Recall the fact that a smooth function can be approximated by a Fourier series, if enough terms are used.

### 7 Binomial Multisection Matching Transformers

The passband response of a binomial transformer is optimum in the sense that, for a given number of sections, the response is flat as possible near the design frequency. Thus, such a response is also known as maximally flat. This type of response is designed, for an  $N$ -section transformer, by setting the first  $N-1$  derivatives of  $|\Gamma(\theta)|$  to zero, at the center frequency  $f_0$ . Such a response can be obtained if

$$\Gamma(\theta) = A(1 + e^{-j2\theta})^N.$$

Then the magnitude  $|\Gamma(\theta)|$  is

$$|\Gamma(\theta)| = |A| |e^{-j\theta} + e^{j\theta}|^N = 2^N |A| |\cos \theta|^N.$$

Note that  $|\Gamma(\theta)| = 0$  for  $\theta = \pi/2$  and that  $(d^n |\Gamma(\theta)|)/d\theta^n = 0$  at  $\theta = \pi/2$  for  $n = 1, 2, \dots, N-1$ . ( $\theta = \pi/2$  corresponds to the center frequency  $f_0$ , for which  $\ell = \lambda/4$  and  $\theta = \beta \ell = \pi/2$ .)

Let  $f \rightarrow 0$ , then  $\theta = \beta \ell = 0$ , and

$$\Gamma(\theta = 0) = A(1 + 1)^N = A2^N = \frac{Z_L - Z_0}{Z_L + Z_0},$$

since for  $f = 0$  all sections are of zero electrical length. Thus,

$$A = 2^{-N} \frac{Z_L - Z_0}{Z_L + Z_0}.$$

Now expanding  $\Gamma(\theta)$  according to the binomial expansion yields

$$\Gamma(\theta) = A(1 + e^{-j2\theta})^N = A \sum_{n=0}^N C_n^N e^{-j2n\theta}, \text{ where } C_n^N = \frac{N!}{(N-n)!n!}. \text{ Since,}$$

$$\Gamma(\theta) = A \sum_{n=0}^N C_n^N e^{-j2n\theta} = \Gamma_0 + \Gamma_1 e^{-j2\theta} + \Gamma_2 e^{-j4\theta} + \dots + \Gamma_N e^{-j2N\theta}, \quad \Gamma_n = AC_n^N.$$

If  $\Gamma_n$ 's are assumed to be small, the following approximation can be applied:

$$\Gamma_n = \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n} \cong \frac{1}{2} \ln \frac{Z_{n+1}}{Z_n}, \text{ since } \ln x \cong 2 \frac{x-1}{x+1}. \text{ Therefore,}$$

$$\ln \frac{Z_{n+1}}{Z_n} \cong 2\Gamma_n = 2AC_n^N = 2(2^{-N}) \frac{Z_L - Z_0}{Z_L + Z_0} C_n^N \cong 2^{-N} C_n^N \ln \frac{Z_L}{Z_0}.$$

To calculate the bandwidth, let  $\Gamma_m$  denote the maximum value of reflection coefficient that can be tolerated over the passband. Then,



$\Gamma_m = 2^N |A| \cos^N \theta_m$ , where  $\theta_m < \pi/2$  is the lower edge of the passband. Thus,

$$\theta_m = \cos^{-1} \left[ \frac{1}{2} \left( \frac{\Gamma_m}{|A|} \right)^{1/N} \right], \text{ and the fractional bandwidth is given by}$$

$$\frac{\Delta f}{f} = \frac{2(f_0 - f_m)}{f_0} = 2 - \frac{4\theta_m}{\pi} = 2 - \frac{4}{\pi} \cos^{-1} \left[ \frac{1}{2} \left( \frac{\Gamma_m}{|A|} \right)^{1/N} \right].$$

**Example 6** Design a three-section transformer to match a  $50 \Omega$  load to a  $100 \Omega$  line, and calculate the bandwidth for  $\Gamma_m = 0.05$ .

## 8 Chebyshev Multisection Matching Transformers

In contrast with the binomial matching transformer, the Chebyshev transformer optimizes bandwidth at the expense of passband ripple. The Chebyshev transformer is designed by equating  $\Gamma(\theta)$  to a Chebyshev polynomial, which has the optimum characteristics needed for this type of transformer.

### Chebyshev Polynomial

The  $n^{\text{th}}$  order Chebyshev polynomial is a polynomial of degree  $n$ , and is denoted by  $T_n(x)$ . The first four Chebyshev polynomials are

$$T_1(x) = x; T_2(x) = 2x^2 - 1; T_3(x) = 4x^3 - 3x; T_4(x) = 8x^4 - 8x^2 + 1.$$

Higher-order polynomials can be found using the following recurrence formula:

$$T_n(x) = 2xT_{n-1}(x) - T_{n-2}(x).$$

Some important properties of Chebyshev polynomials are listed here:

1. For  $-1 \leq x \leq 1$ ,  $|T_n(x)| \leq 1$ . In this range, the Chebyshev polynomials oscillate between  $\pm 1$ . This is the equal ripple property, and this region will be mapped to the passband of the matching transformer.
2. For  $|x| > 1$ ,  $|T_n(x)| > 1$ . This region will be mapped to the frequency range outside the passband.
3. For  $|x| > 1$ ,  $|T_n(x)|$  increases faster with  $x$  as  $n$  increases.

Now, let  $x = \cos \theta$  for  $|x| < 1$ . Then it can be shown that the Chebyshev polynomials can be expressed as

$$T_n(\cos \theta) = \cos n\theta, \text{ or more generally as}$$

$$T_n(x) = \begin{cases} \cos(n \cos^{-1} x) & \text{for } |x| < 1 \\ \cosh(n \cosh^{-1} x) & \text{for } |x| > 1 \end{cases}$$

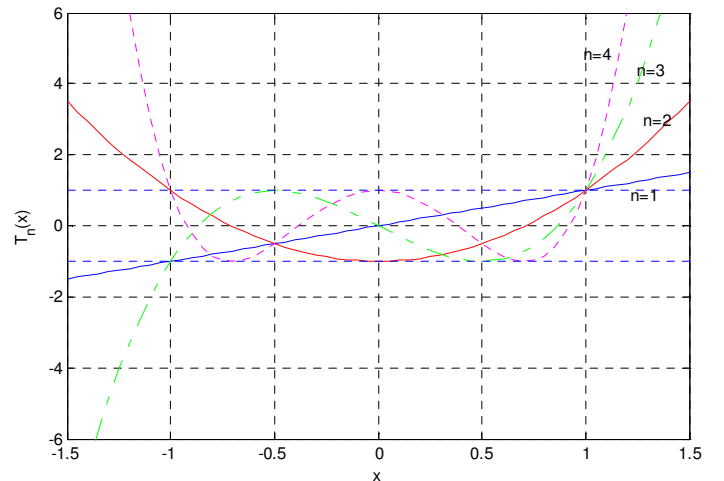


Fig. 8: First four Chebyshev polynomials

Since equal ripple is desirable in the passband, it is necessary to map  $\theta_m$  to  $x = 1$  and  $\pi - \theta_m$  to  $x = -1$ , where  $\theta_m$  and  $\pi - \theta_m$  are the lower and upper edges of the passband. This can be accomplished by replacing  $\cos \theta$  in the above equation with  $\cos \theta / \cos \theta_m$ :

$$T_n \left( \frac{\cos \theta}{\cos \theta_m} \right) = T_n(\sec \theta_m \cos \theta) = \cos n \left[ \cos^{-1} \left( \frac{\cos \theta}{\cos \theta_m} \right) \right].$$

Then  $|\sec \theta_m \cos \theta| \leq 1$  for  $\theta_m < \theta < \pi - \theta_m$ , so  $|T_n(\sec \theta_m \cos \theta)| \leq 1$  over this same range.

It follows that the first four terms of the Chebyshev polynomials can be written as

$$T_1(\sec \theta_m \cos \theta) = \sec \theta_m \cos \theta; T_2(\sec \theta_m \cos \theta) = \sec^2 \theta_m (\cos 2\theta + 1) - 1;$$

$$T_3(\sec \theta_m \cos \theta) = \sec^3 \theta_m (\cos 3\theta + 3 \cos \theta) - 3 \sec \theta_m \cos \theta;$$

$$T_4(\sec \theta_m \cos \theta) = \sec^4 \theta_m (\cos 4\theta + 4 \cos 2\theta + 3) - 4 \sec^2 \theta_m (\cos 2\theta + 1) + 1.$$

The above results can be used to design matching transformers with up to four sections.

#### Design of Chebyshev Transformers

A Chebyshev equal-ripple passband can be synthesized by making  $\Gamma(\theta)$  proportional to  $T_N(\sec \theta_m \cos \theta)$ , where  $N$  denotes the number of sections. Thus,

$$\Gamma(\theta) = 2e^{-jN\theta} \{ \Gamma_0 \cos N\theta + \Gamma_1 \cos(N-2)\theta + \dots + \Gamma_n \cos(N-2n)\theta + \dots \} = Ae^{-jN\theta} T_N(\sec \theta_m \cos \theta)$$

where the last term in the series is  $(1/2)\Gamma_{N/2}$  for  $N$  even and  $\Gamma_{(N-1)/2} \cos \theta$  for  $N$  odd. The constant  $A$  can be found from letting  $\theta = 0$ :

$$\Gamma(\theta = 0) = \frac{Z_L - Z_0}{Z_L + Z_0} = AT_N(\sec \theta_m), \text{ or } A = \frac{Z_L - Z_0}{Z_L + Z_0} \frac{1}{T_N(\sec \theta_m)}.$$

Now if the maximum allowable reflection coefficient magnitude in the passband is  $\Gamma_m$  (i.e., the *ripple*), then  $\Gamma_m = |A|$ , since the maximum value of  $T_N(\sec \theta_m \cos \theta)$  in the passband is unity. Using the approximation introduced in the previous section yields

$$T_N(\sec \theta_m) = \frac{1}{\Gamma_m} \left| \frac{Z_L - Z_0}{Z_L + Z_0} \right| \cong \frac{1}{2\Gamma_m} \left| \ln \frac{Z_L}{Z_0} \right|. \text{ It follows that}$$

$$\sec \theta_m = \cosh \left\{ \frac{1}{N} \cosh^{-1} \left( \frac{1}{\Gamma_m} \left| \frac{Z_L - Z_0}{Z_L + Z_0} \right| \right) \right\} \cong \cosh \left\{ \frac{1}{N} \cosh^{-1} \left( \left| \frac{\ln(Z_L / Z_0)}{2\Gamma_m} \right| \right) \right\}.$$

Once  $\theta_m$  is known, the fractional bandwidth can be calculated from

$$\frac{\Delta f}{f} = 2 - \frac{4\theta_m}{\pi}.$$

Each  $\Gamma_n$  can be determined by expanding  $T_N(\sec \theta_m \cos \theta)$  and equating similar terms of the form  $\cos(N-2n)\theta$ . The following approximation can be applied to improve the accuracy:

$$\Gamma_n = \frac{Z_{n+1} - Z_n}{Z_{n+1} + Z_n} \cong \frac{1}{2} \ln \frac{Z_{n+1}}{Z_n}.$$

**Example 7** Design a three-section Chebyshev transformer to match a  $100 \Omega$  load to a  $50 \Omega$  line, with  $\Gamma_m = 0.05$ .